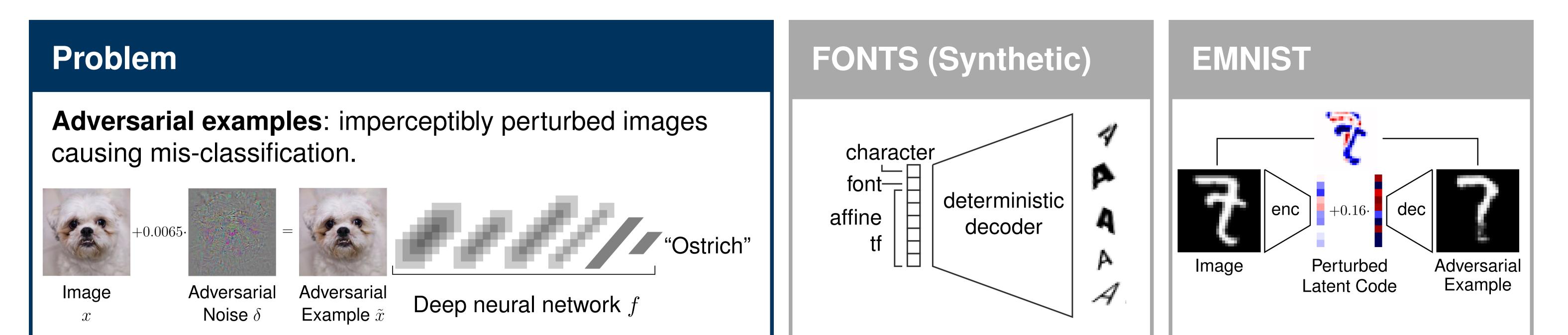


# Disentangling Adversarial Robustness and Generalization

David Stutz, Matthias Hein and Bernt Schiele



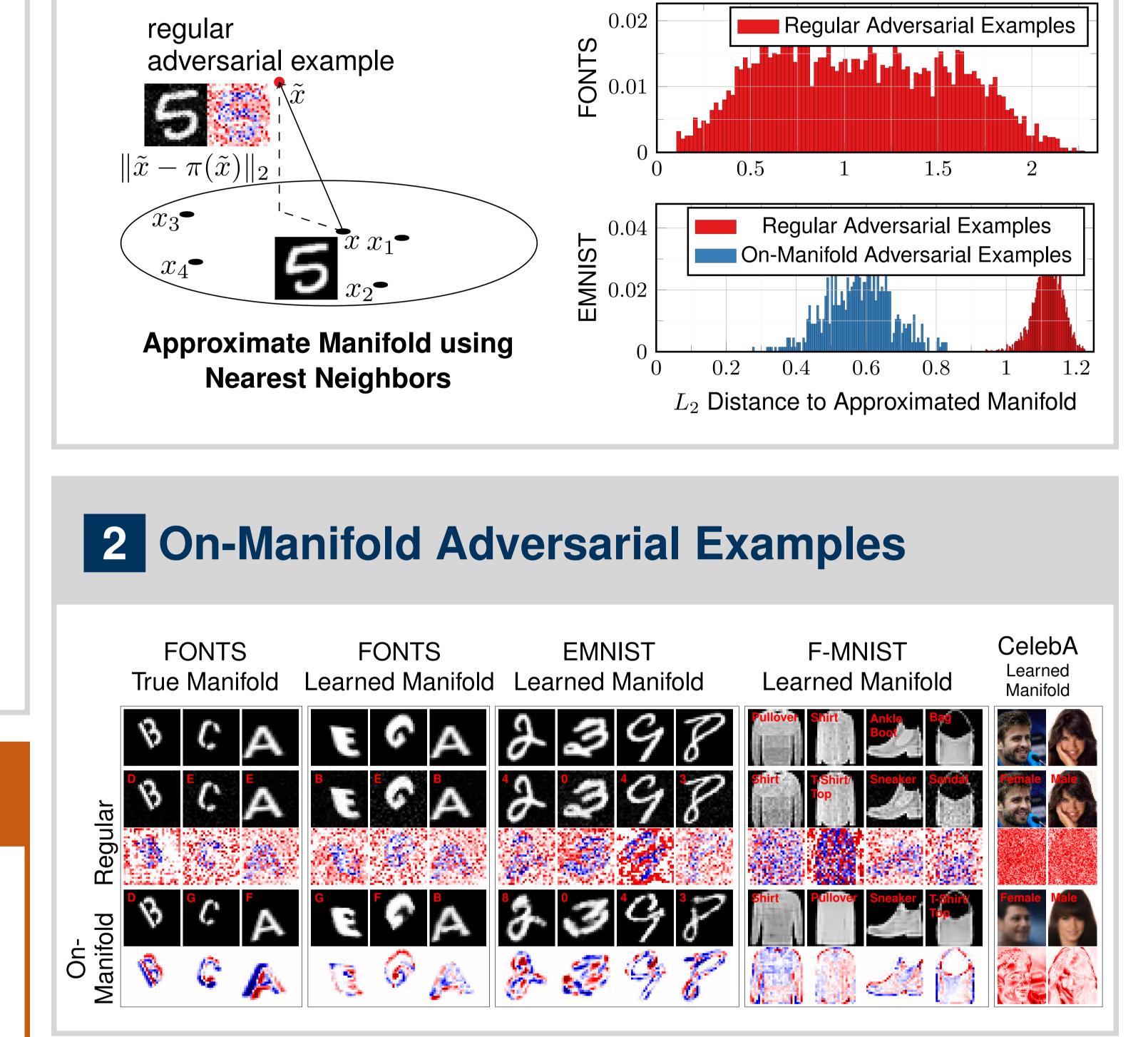




### Background

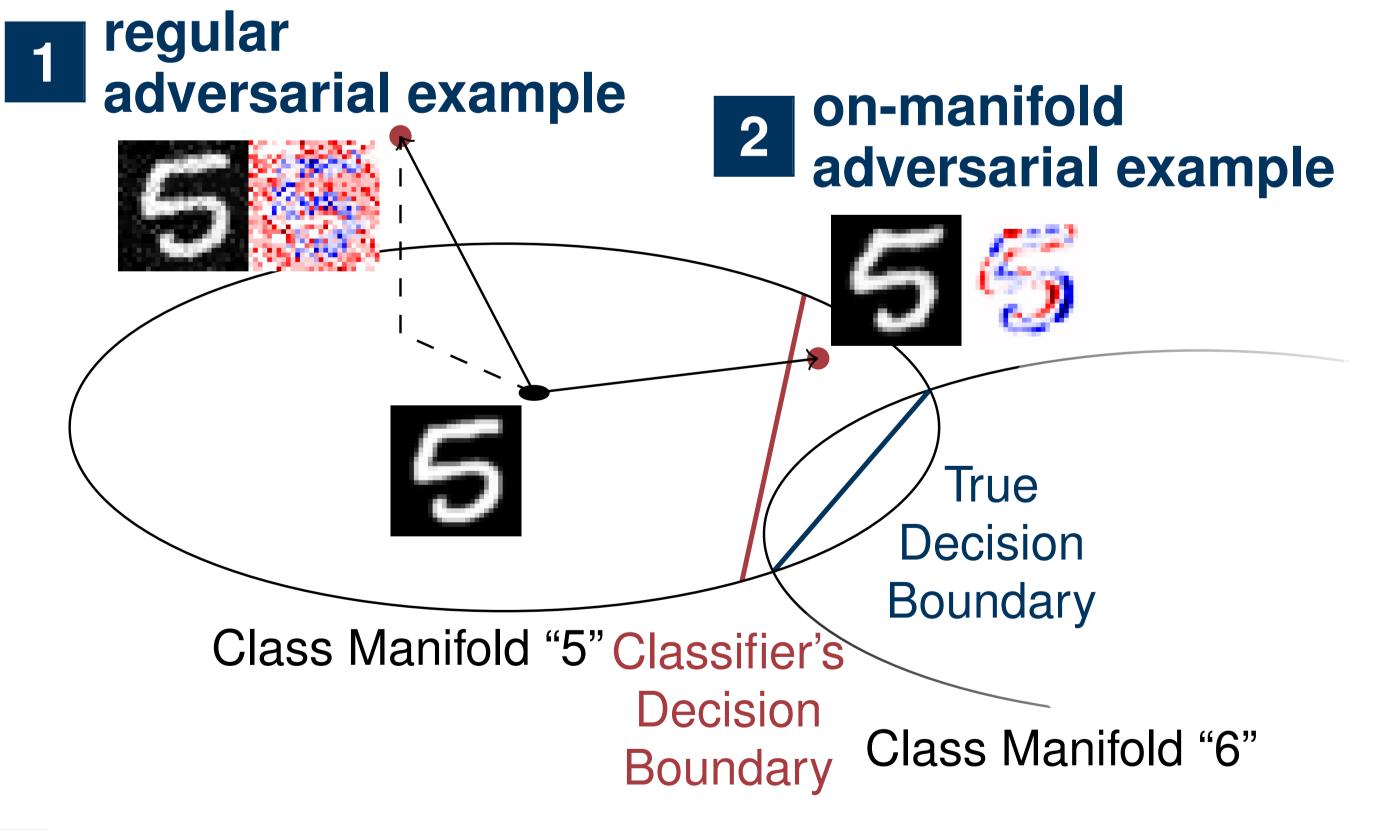
Deep neural networks (simplified): Element-wise activation function  $f(x;w) = h(w_L^T h(w_{L-1}^T h(\dots h(w_1^T x))))$ Set of weight matrices  $\{w_l\}_{l=1}^L$ Training with dataset  $\{(x_n, y_n)\}_{n=1}^N$ : Target label  $y_n$  for input  $x_n$   $w^* = \underset{w}{\operatorname{argmin}} \sum_n \mathcal{L}(f(x_n;w), y_n)$   $cross-entropy loss <math>\mathcal{L}$ Adversarial examples: Maximize loss w.r.t. true label y  $\tilde{x} = x + \delta$  with  $\delta = \underset{\|\delta\|_{\infty} \leq \epsilon}{\operatorname{argmax}} \mathcal{L}(f(x + \delta; w^*), y)$ "Imperceptible" adversarial noise

# **1** Adversarial Examples Leave Manifold



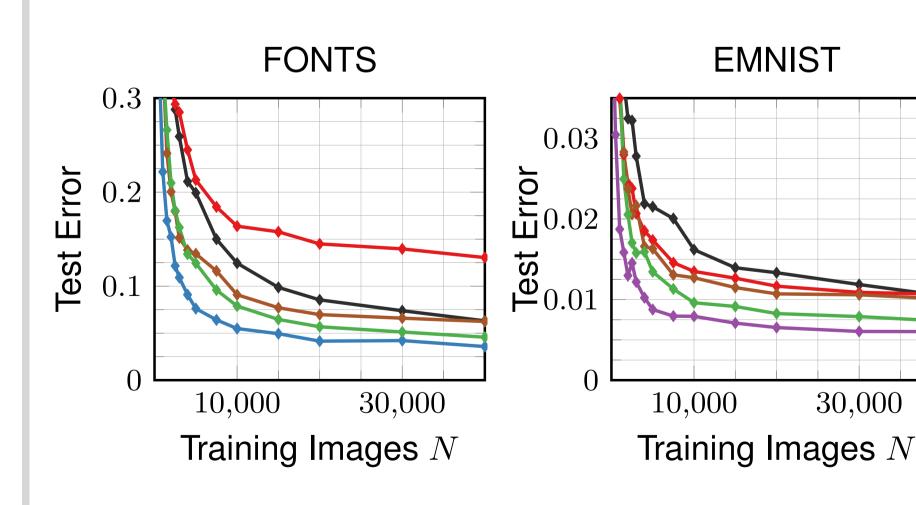
#### Contributions

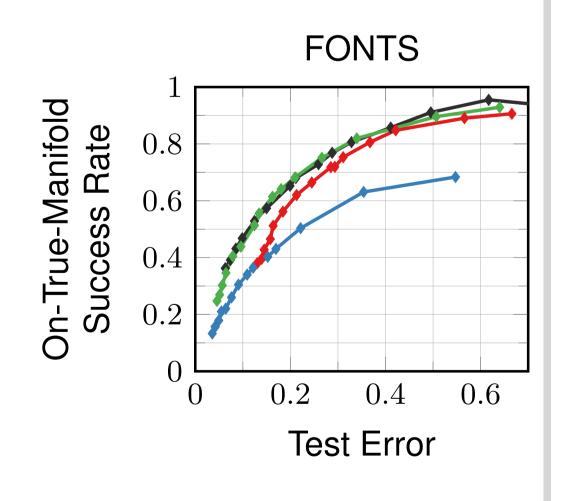
Are accurate and robust models possible?



**3** On-manifold robustness *is* generalization.

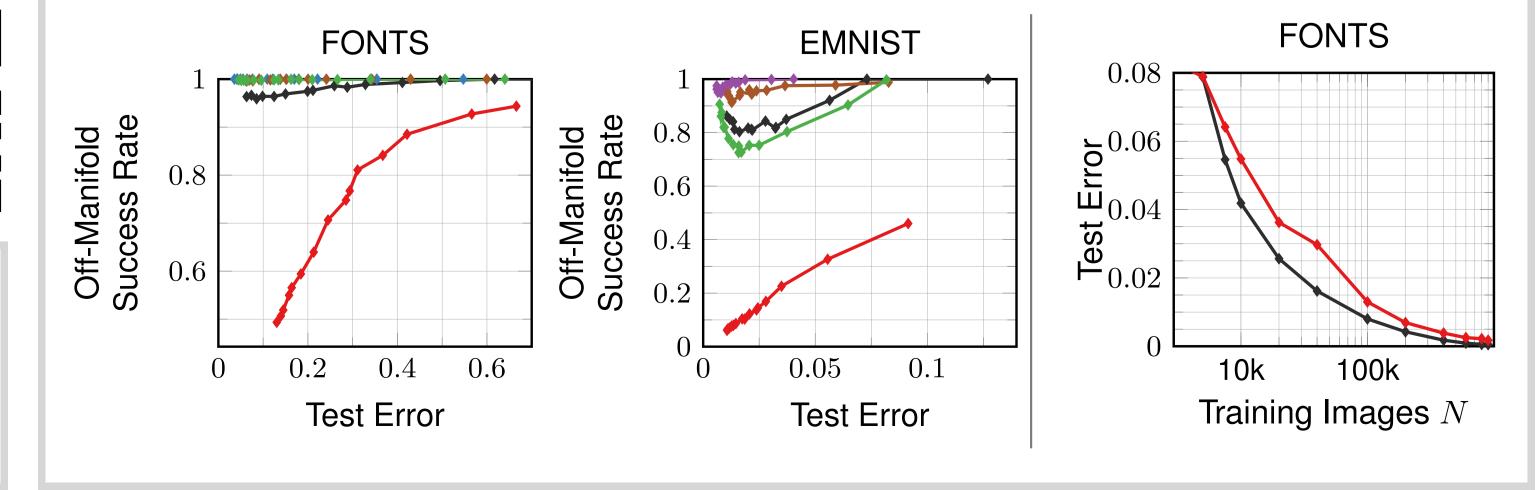
# **3** On-Manifold Robustness *is* Generalization





4 Robustness and generalization *not* contradicting.
▶ Robustness has higher sample complexity.

# **4** Robustness Independent of Generalization



Paper, Code and Data: davidstutz.de/hlf2019



Normal Training
Adversarial Training
Adversarial Training w/ On-*True*-Manifold Adversarial Examples
Adversarial Training w/ On-*Learned*-Manifold Adversarial Examples
Adversarial Training w/ Adversarial Transformations